

MULTICHANNEL RNN-BASED SEPARATION OF OVERLAPPING SPEECH

Lauréline Perotin^{†‡}, Romain Serizel[‡], Emmanuel Vincent[‡], Alexandre Guérin[†]

[†]Orange Labs

[‡]Université de Lorraine, Inria, LORIA



PROBLEM STATEMENT

Distant-microphone voice command for personal digital assistant

- Real room conditions
 - Competing speakers
 - Ambient babble noise
- Enhance the target speaker



PROBLEM STATEMENT

State of the art: Neural networks to estimate time-frequency masks or multichannel filter parameters

Current challenges: Overlapping speech

Contributions:

- Ambisonics contents
- Multi-source localization
- Enhancement in overlapping speech conditions by estimating the parameters of a multichannel filter

1. HIGH ORDER AMBISONICS

Capture



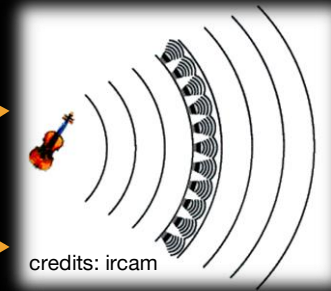
Ambeo

Eigenmike



HOA

Rendering



Wave
Field
Synthesis

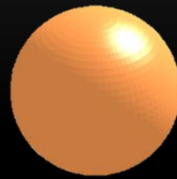
binaural



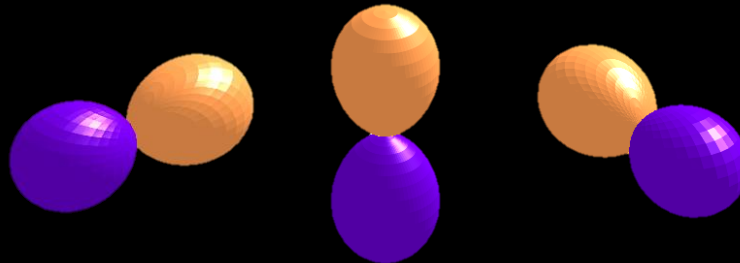
5.1,
ATMOS...

1. HIGH ORDER AMBISONICS

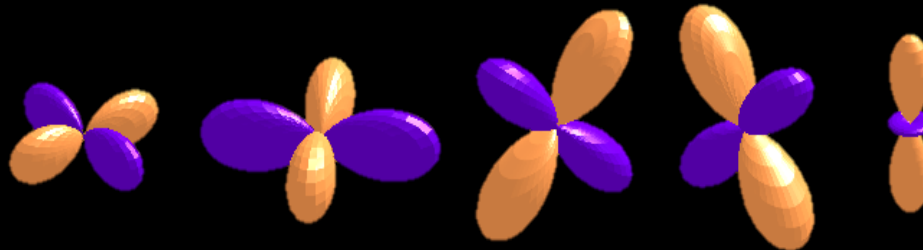
Order 0



Order 1



Order 2



...

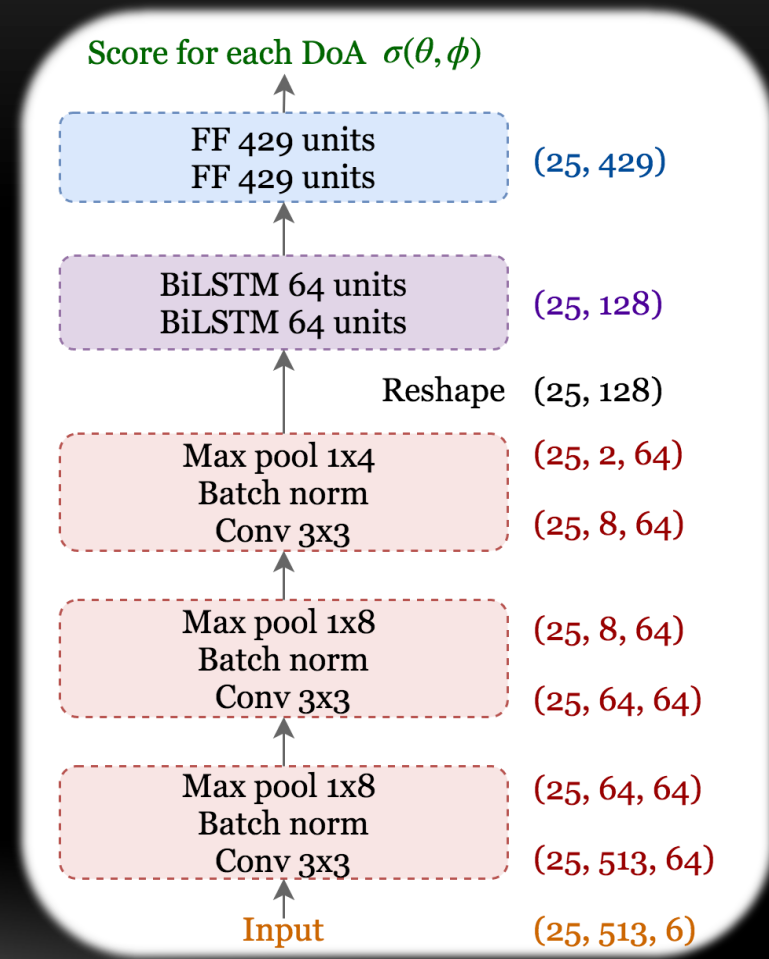
4 channels
W, X, Y, Z
≈ 4 virtual mics

2. PROPOSED SOLUTION FOR DIRECTION-OF-ARRIVAL ESTIMATION

Input feature based on acoustic intensity:

$$\mathbf{I}_a(t, f) = \begin{bmatrix} \mathcal{R}\{W(t, f)^* X(t, f)\} \\ \mathcal{R}\{W(t, f)^* Y(t, f)\} \\ \mathcal{R}\{W(t, f)^* Z(t, f)\} \end{bmatrix}$$

$$\mathbf{I}_r(t, f) = \begin{bmatrix} \mathcal{I}\{W(t, f)^* X(t, f)\} \\ \mathcal{I}\{W(t, f)^* Y(t, f)\} \\ \mathcal{I}\{W(t, f)^* Z(t, f)\} \end{bmatrix}$$



3. ENHANCEMENT: FULL-BAND BEAMFORMING



Mixture: $\mathbf{x}(t, f) = \mathbf{s}(t, f) + \mathbf{n}(t, f)$

HOA anechoic mixing matrix:

$$\mathbf{A} = \begin{bmatrix} 1 & \dots & 1 \\ \sqrt{3} \cos \theta_0 \cos \phi_0 & \dots & \sqrt{3} \cos \theta_J \cos \phi_J \\ \sqrt{3} \sin \theta_0 \cos \phi_0 & \dots & \sqrt{3} \sin \theta_J \cos \phi_J \\ \sqrt{3} \sin \phi_0 & \dots & \sqrt{3} \sin \phi_J \end{bmatrix}$$

HOA beamformer: $\hat{\mathbf{s}}(t, f) = \mathbf{u}_1^T \mathbf{A}^\dagger \mathbf{x}(t, f)$

→ not robust to reverberation and close speakers



3. ENHANCEMENT: MULTICHANNEL WIENER FILTERING



Mixture: $\mathbf{x}(t, f) = \mathbf{s}(t, f) + \mathbf{n}(t, f)$

Time-invariant multichannel Wiener filter:

$$\mathbf{w}(f) = [\Phi_{\mathbf{ss}}(f) + \Phi_{\mathbf{nn}}(f)]^{-1} \Phi_{\mathbf{ss}}(f) \mathbf{u}_1$$

→ Little distortion, but covariance matrices needed!

Mask – based covariance estimation:

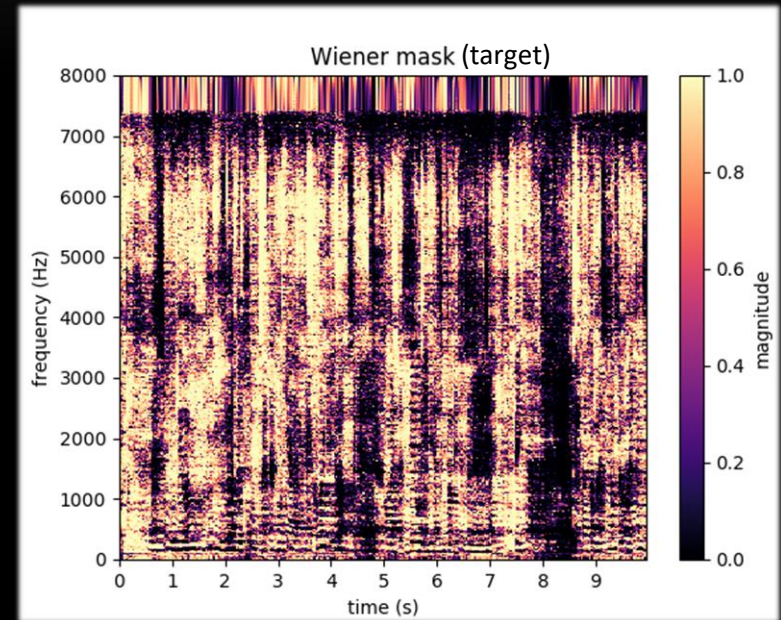
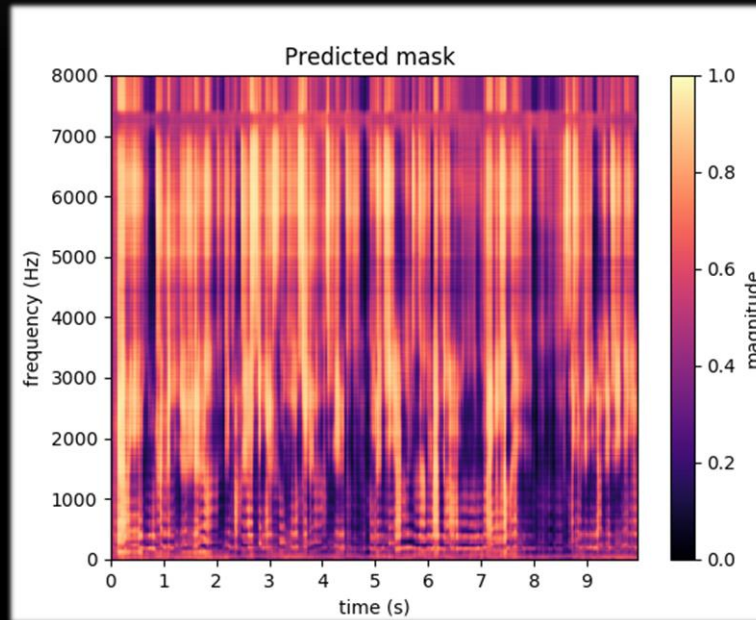
$$M_s(t, f) = \frac{|s(t, f)|}{|s(t, f)| + |n(t, f)|}$$

$$\tilde{\mathbf{s}}(t, f) = M_s(t, f) \mathbf{x}(t, f)$$

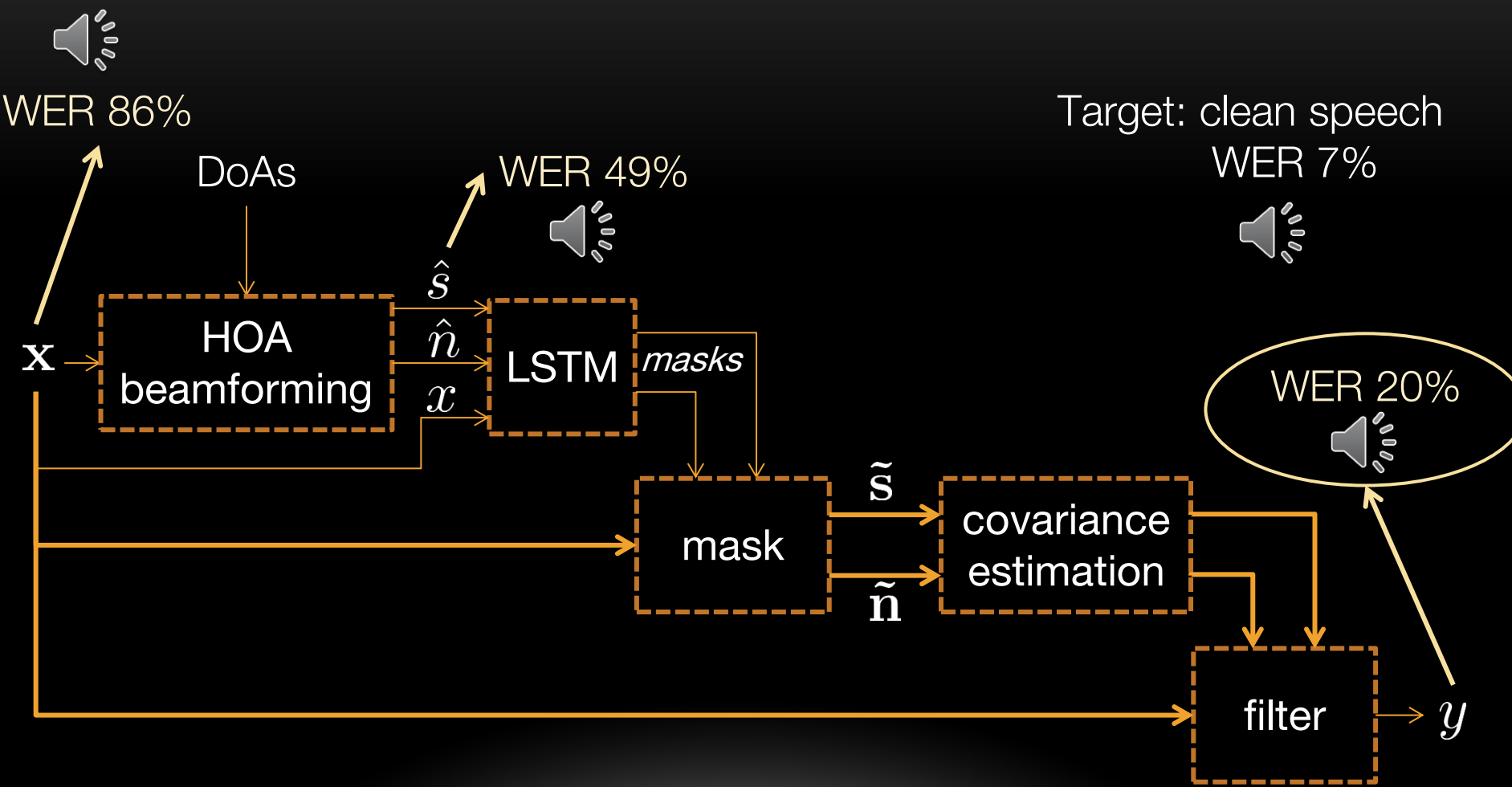
$$\left. \begin{array}{l} M_s(t, f) = \frac{|s(t, f)|}{|s(t, f)| + |n(t, f)|} \\ \tilde{\mathbf{s}}(t, f) = M_s(t, f) \mathbf{x}(t, f) \end{array} \right\} \tilde{\Phi}_{\mathbf{ss}}(f) = \frac{1}{T} \sum_{t=0}^{T-1} \tilde{\mathbf{s}}(t, f) \tilde{\mathbf{s}}^H(t, f)$$

3. PROPOSED SOLUTION

Estimation of the mask via LSTM neural network:



3. PROPOSED SOLUTION



3. RESULTS FOR LOCALIZATION

Test data :

2 overlapping speakers, static, no VAD

25 to 90° angular distance

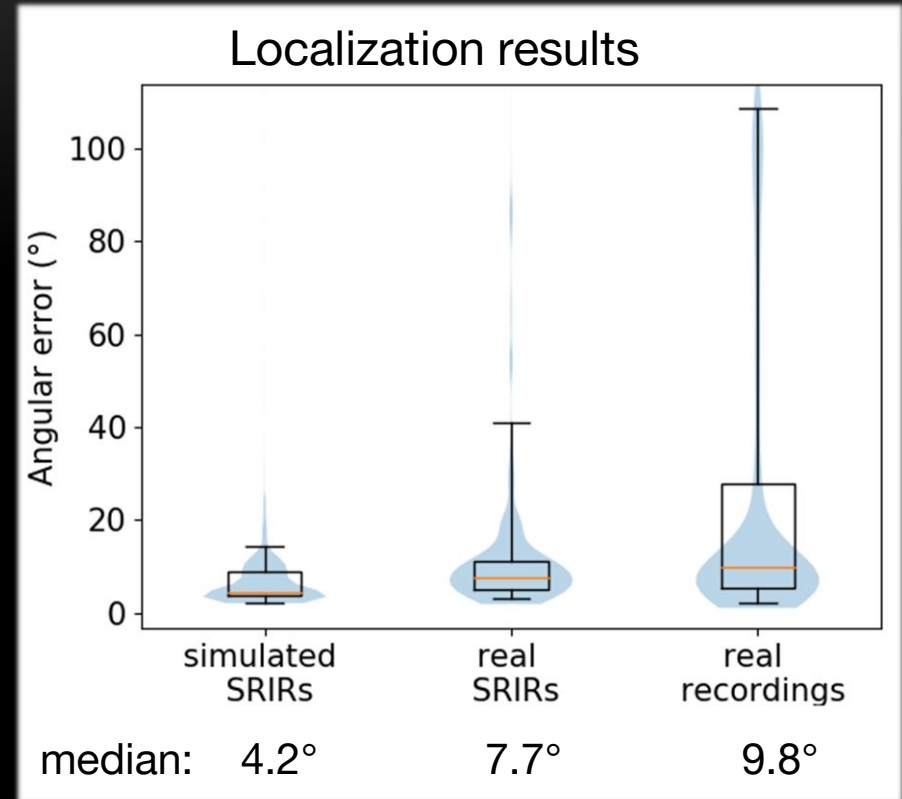
SIR = 0 dB, SNR = 20 dB

- Simulated SRIRs (image method)
RT60 = 0.2 to 0.8s
- Real SRIRs
RT60 ≈ 0.5s
random source/mic orientations
- Real recordings
living-room, mic on coffee table

Training data :

SIR = 0 to 10 dB, SNR = 20 dB, different speakers and rooms

36 h of speech made from simulated SRIRs



3. RESULTS FOR ENHANCEMENT

Word Error Rate (%)	Simulated SRIRs	Real SRIRs	Real recordings
Clean speech	7.4	7.4	n/a
Mixture	81.9	86.0	89.5
Oracle DoA + beamformer	32.3	49.2	53.8
Oracle DoA + proposed filter	12.3	19.7	20.3
Estimated DoA + beamformer	33.1	53.1	57.9
Estimated DoA + proposed filter	13.4	25.3	26.5

Training data

10h of mixed speech at SIR = 0 dB

44 different speakers

16 positions in a single room at $RT_{60} = 270\text{ms}$

CONCLUSION

order 1 Ambisonics
2 speakers + noise

Directions
of arrival
by CRNN

LSTM-based multichannel Wiener filter

Inputs: omnidirectional mixture
+ beamformer toward target speech
+ beamformer toward competing speech

Largely outperforms beamforming or
sole masking, including with close
speakers in real conditions